

BIDIRECTIONAL INTERPOLATION FOR THE λ -CALCULUS

LHC Days – June 18th 2026

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- $\text{voc}(M) \subseteq \text{voc}(F) \cap \text{voc}(G)$

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A **factorisation** property of sorts (ask Noam for the categorical view)... which logicians **love**!

INTERPOLATION

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A **factorisation** property of sorts (ask Noam for the categorical view)... which logicians **love**!

Alexis (a logician): “It would be cool to prove an interpolation theorem for dependent types!”

Me (a type theorist): “Sure, how does an interpolation proof look like?”

Simply-typed λ -calculus ($\times, \top, \rightarrow, +, \perp$) has the interpolation property (Čubrić, 1994)

If $x: A \vdash t : B$ then there exist M, r, l such that:

- $x: A \vdash l : M$
- $y: M \vdash r : B$
- $r[l] \equiv t$
- $\text{voc}(M) \subseteq \text{voc}(A) \cap \text{voc}(B)$ (base types appearing in M appear both in A and B)

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Internal language of biCCCs $\rightarrow$ nice consequences for the bicategory of biCCCs

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Internal language of biCCCs $\rightarrow$ nice consequences for the bicategory of biCCCs

Great! Or?

Simply

If $x: A \vdash$

- $x: A$
- $y: M$
- $r[l] \equiv$
- $\text{voc}(l)$

Internal la

Great! Or?

First we need the following lemma (cf. [Pra65, Cor. 3, p. 54]).

Lemma 3.5. For a free $\lambda\delta$ -calculus (no additional equations but with constants) the following holds: let t^c be a ρ -normal term which is one of: $\pi_i(s)$, $s'r$, $\delta x \cdot u$, $y \cdot v$; s , $\varepsilon^c(s)$ or an atomic term (i.e. a variable or a constant (or $*$)). Then there exists a chain $t \equiv t_0 > \dots > t_n$ of successive subterms of t such that they are in the following relation: for every $0 \leq i < n$, t_i is one of $\pi_j(t_{i+1})$, $t_{i+1} \cdot u$, $\delta x \cdot u$, $y \cdot v$; t_{i+1} (for some u, v, x and y) or $t_i \equiv \varepsilon^B(t_{i+1})$, and moreover t_n is an atomic term (i.e. $t_n \equiv v^E$ where v is a variable or a constant (or $*$)).

In particular if the term t is not $*$ then t_n is not $*$. So, if in addition the $\lambda\delta$ -calculus doesn't have constants then t_n is a variable.

Furthermore, by C-normality we have: if $t_{n-1} \equiv \delta x \cdot u$, $y \cdot v$; t_n then the above chain $t \equiv t_0 > \dots > t_n$ is actually just $t \equiv \delta x \cdot u$, $y \cdot v$; t_1 and t_1 is either $x^{E_1 + E_2}$ or a constant (for some ρ -normal terms u, v).

Similarly, by E-normality, if $t_{n-1} \equiv \varepsilon^B(t_n)$ then $t \equiv \varepsilon^B(t_1)$ and t_1 is a variable x^0 or a constant of type 0.

Case 6: (In this case only, we use Lemma 3.5.) $t \equiv \pi_i(s)$ or $t \equiv s'r$ or $t \equiv \delta x \cdot u$, $y \cdot v$; s or $t \equiv \varepsilon^C(s)$ where r, s, u and v are some ρ -normal terms. Then by Lemma 3.5 we have that there exists a chain of immediate subterms: $t \equiv t_0 > t_1 > \dots > t_i > \dots > t_n$ such that the following subcases can take place: $t_{n-1} \equiv \pi_i(x^{E_1 \times E_2})$ or $t_{n-1} \equiv x^{E_1 \times E_2} u^{E_2}$ or $t_{n-1} \equiv \delta x \cdot u$, $y \cdot v$; $x^{E_1 \times E_2}$ or $t_{n-1} \equiv \varepsilon^B(x^0)$ for some ρ -normal terms u and v since in the calculus we don't have additional constants and $t \neq *$.

Subcase 6.1.1: $t_{n-1} \equiv \pi_i(x^{E_1 \times E_2})$ and $x^{E_1 \times E_2} \in \Gamma_1$.

Let t' be like the term t except that it has x^{E_i} instead of t_{n-1} (notice however, that t' can contain $x^{E_1 \times E_2}$) so $t \equiv_r t'(\pi_i(x^{E_1 \times E_2})/x^{E_i})$. The complexity of t' is lower than the complexity of t , so we can apply the induction hypothesis on $(\Gamma \cup \{x^{E_i}\} \triangleright t')$ and the partition $\Gamma, x^{E_i} = (\Gamma_1, x^{E_i}) \cup \Gamma_2$. Then by the induction hypothesis then exist $(\Gamma_1, x^{E_i} \triangleright R^A)$ and $(\Gamma_2, y^A \triangleright S^C)$ such that

$$(i) \quad t' =_{r, x^{E_i}} S(R/y), \quad A^+ \subseteq (\Gamma_1 \cup E_i)^+ \cap (\Gamma_2^- \cup C^+), \quad A^- \subseteq (\Gamma_1 \cup E_i)^- \cap (\Gamma_2^+ \cup C^-).$$

Recall that $x^{E_1 \times E_2}$ is in Γ_1 . So we define $r = R(\pi_i(x^{E_1 \times E_2}))$, $s = S$ and A stays the same and we can check that the lemma is satisfied. First:

$$t =_r t'(\pi_i(x^{E_1 \times E_2})/x^{E_i}) =_r S((R(\pi_i(x^{E_1 \times E_2}))/x^{E_i}))/y \equiv s(r/y).$$

The second and third part of the conclusion are satisfied since $E_i^s \subset (E_1 \times E_2)^s$ where $s = +, -$. It is obvious that the stronger hypothesis gives the reduction instead of the equality.

Simply

If $x: A \vdash$

- $x: A$
- $y: M$
- $r[l]$
- $\text{voc}(l)$

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Great! Or?

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Case 6: (In this case only, we use Lemma 3.5.) $t \equiv \pi_i(s)$ or $t \equiv s'r$ or $t \equiv \delta x.u$, $y.v$; s or $t \equiv \varepsilon^C(s)$ where r, s, u and v are some ρ -normal terms. Then by Lemma 3.5 we have that there exists a chain of immediate subterms: $t \equiv t_0 > t_1 > \dots > t_i > \dots > t_n$ such that the following subcases can take place: $t_{n-1} \equiv \pi_i(x^{E_1 \times E_2})$ or $t_{n-1} \equiv x^{E_1 \times E_2}$ or $t_{n-1} \equiv \varepsilon^B(x^0)$ for some ρ -normal term $x^{E_1 \times E_2}$ and constants and $t \not\equiv *$.

Subcase 6.1.1: $t_{n-1} \equiv \pi_i(x^{E_1 \times E_2})$

Let t' be like t

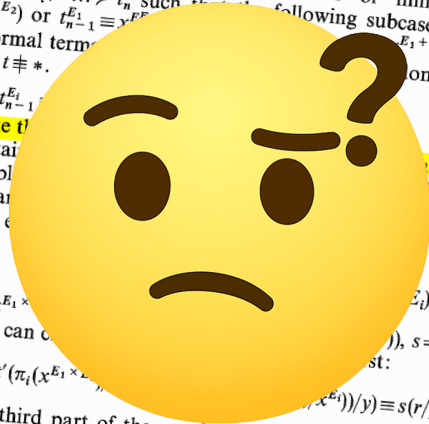
that t' can contain t then the complexity of t' is lower than the complexity of t hypothesis then $t' \equiv t$

(i) $t' =_{r, x^{E_1 \times E_2}} S(R/y)$

Recall that $x^{E_1 \times E_2}$ is the same and we can

$t =_r t'(\pi_i(x^{E_1 \times E_2})/y) \equiv s(r/y)$.

The second and third part of the conclusion are satisfied since $E_i^s \subset (E_1 \times E_2)^s$ where $s = +, -$. It is obvious that the stronger hypothesis gives the reduction instead of the equality.



994)

THAT'S JUST NEUTRAL TERMS!

$$\frac{}{nf *}$$

$$\frac{nf\ t \quad nf\ u}{nf\ (t, u)}$$

$$\frac{nf\ t}{nf\ \lambda x. t}$$

$$\frac{ne\ t}{nf\ t}$$

$$\frac{}{ne\ x}$$

$$\frac{ne\ p}{ne\ p. i}$$

$$\frac{ne\ t \quad nf\ u}{ne\ t\ u}$$

THAT'S JUST NEUTRAL TERMS!

$$\begin{array}{c} \frac{}{\text{nf } *} \end{array} \qquad \frac{\text{nf } t \quad \text{nf } u}{\text{nf } (t, u)} \qquad \frac{\text{nf } t}{\text{nf } \lambda x. t} \qquad \frac{\text{ne } t}{\text{nf } t}$$
$$\frac{}{\text{ne } x} \qquad \frac{\text{ne } p}{\text{ne } p. i} \qquad \frac{\text{ne } t \quad \text{nf } u}{\text{ne } t \ u}$$

Why neutrals/normals?

THAT'S JUST NEUTRAL TERMS!

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Why neutrals/normals?

Because they represent equivalence classes for $\equiv_\beta$

THAT'S JUST NEUTRAL TERMS!

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Why neutrals/normals?

Because they represent equivalence classes

Because they have a good **subformula property** $\rightarrow$ formulas always come from somewhere



I don't want invented
formulas to control
their vocabulary



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It's the same thing!

Normal forms check, neutrals infer

ENTER BIDIRECTIONAL TYPING

$\boxed{\Gamma \vdash t \triangleleft A}$ Normal/checking forms $t, u, \dots \in \text{Nf}(\Gamma, A)$

$$\frac{}{\Gamma \vdash * \triangleleft \top}$$

$$\frac{\Gamma \vdash t \triangleleft A \quad \Gamma \vdash u \triangleleft B}{\Gamma \vdash (t, u) \triangleleft A \times B}$$

$$\frac{\Gamma, x:A \vdash t \triangleleft B}{\Gamma \vdash \lambda x. t \triangleleft A \rightarrow B}$$

$$\frac{\Gamma \vdash t \triangleright A \quad A = B}{\Gamma \vdash \underline{t} \triangleleft B}$$

Normal forms check, neutrals infer

$\boxed{\Gamma \vdash t \triangleright A}$ Neutral/infering forms $t, u, \dots \in \text{Ne}(\Gamma, A)$

$$\frac{(x:A) \in \Gamma}{\Gamma \vdash x \triangleright A}$$

$$\frac{\Gamma \vdash p \triangleright A_1 \times A_2}{\Gamma \vdash p.i \triangleright A_i}$$

$$\frac{\Gamma \vdash t \triangleright A \rightarrow B \quad \Gamma \vdash u \triangleleft A}{\Gamma \vdash t u \triangleright B}$$

Normalisation

For any term $\Gamma \vdash t : A$, there exists t' such that $\Gamma \vdash t' \triangleleft A$ and $t \rightsquigarrow_{\beta}^* t'$.

Logical relations/reducibility/..., nothing new

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Interpolation

Assume a partitioned context $\Gamma = \Gamma_s \cup \Gamma_t$.

Given any $\Gamma \vdash t \triangleleft T$, there is a type M and terms $\Gamma_s \vdash l : M$ and $\Gamma_t.(x : M) \vdash r : T$ such that $r[l] \equiv t$ and $\text{voc}(M) \subseteq \text{voc}(\Gamma_s) \cap (\text{voc}(\Gamma_t) \cup \text{voc}(T))$.

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Given any $\Gamma \vdash t \triangleleft T$, there is a type M and terms $\Gamma_s \vdash l : M$ and $\Gamma_t.(x : M) \vdash r : T$ such that $r[l] \equiv t$ and $\text{voc}(M) \subseteq \text{voc}(\Gamma_s) \cap (\text{voc}(\Gamma_t) \cup \text{voc}(T))$.

Mutual induction: given any $\Gamma \vdash t \triangleright T$, either

- $\text{voc}(T) \subseteq \text{voc}(\Gamma_s)$, and we have a type M and terms $\Gamma_t \vdash l : M$ and $\Gamma_s.(x : M) \vdash r : T$ such that $r[l] \equiv t$ and $\text{voc}(M) \subseteq \text{voc}(\Gamma_s) \cap \text{voc}(\Gamma_t)$.
- or $\text{voc}(T) \subseteq \text{voc}(\Gamma_t)$, and we have a type M and $\Gamma_s \vdash l : M$ and $\Gamma_t.(x : M) \vdash r : T$ such that $r[l] \equiv t$ and $\text{voc}(M) \subseteq \text{voc}(\Gamma_s) \cap \text{voc}(\Gamma_t)$.

AND SUMS?

$$\frac{\Gamma \vdash t : \perp}{\Gamma \vdash \text{raise } t : T}$$

$$\frac{\Gamma \vdash s : A + B \quad \Gamma.(x:A) \vdash b_l : T \quad \Gamma.(x:B) \vdash b_r : T}{\Gamma \vdash \text{if}(s, b_l, b_r) : T}$$

AND SUMS?



The elimination rules are very bad. What is catastrophic about them is the parasitic presence of a formula T which has no structural link with the formula which is eliminated.

– Proofs and Types

$b_r : T$

AND SUMS?

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...

$$\frac{\Gamma \vdash a \triangleleft A}{\Gamma \vdash \text{inl } a \triangleleft A + B}$$

$$\frac{\Gamma \vdash b \triangleleft B}{\Gamma \vdash \text{inr } b \triangleleft A + B}$$

$$\frac{\Gamma \vdash t \triangleright \perp}{\Gamma \vdash \text{raise } t \triangleleft A}$$

$$\frac{\begin{array}{c} \Gamma \vdash s \triangleright A + B \\ \Gamma.(x:A) \vdash b_l \triangleleft T \quad \Gamma.(x:B) \vdash b_r \triangleleft T \end{array}}{\Gamma \vdash \text{if}(s, b_l, b_r) \triangleleft T}$$

Good subformula property, although not canonical representatives

...

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$$\frac{\Gamma \vdash s \triangleright A + B \quad \Gamma.(x:A) \vdash b_l \triangleleft T \quad \Gamma.(x:B) \vdash b_r \triangleleft T}{\Gamma \vdash \text{if}(s, b_l, b_r) \triangleleft T}$$

Good subformula property, although not canonical representatives

Normalisation up to β and **commuting conversion**

$$\begin{aligned} (\text{raise } t) u &\rightsquigarrow^* \text{raise } t \\ \text{if}(t, b_l, b_r) u &\rightsquigarrow^* \text{if}(t, b_l u, b_r u) \end{aligned}$$

Normalization by Evaluation for Call-By-Push-Value and Polarized λ -Calculus (Abel et al. 2019)

A NEW ENTRY IN THE CURRY-HOWARD DICTIONARY?

“Cut-free proofs have a good subformula property... but sum elimination complicates it.”

“Bidirectional typing works well for normal forms... but pattern-matching complicates it.”

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Thank you!

All formalised in Rocq, there's a paper at ITP '26